

Application des éléments discrets et de la reconstruction par covariants à la modélisation de l'endommagement anisotrope

Réunion thématique du GDR-GDM, ENS Paris-Saclay, 23/11/2022.

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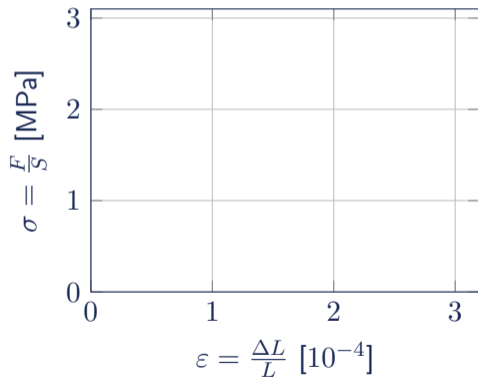
Context

Quasi-brittle materials: Observations

An exemple of structure



A tensile test on concrete (Terrien, 1980)

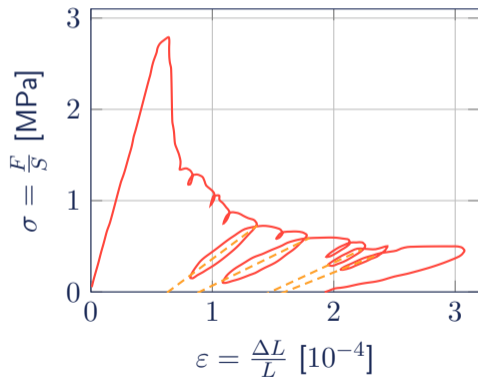


Quasi-brittle materials: Observations

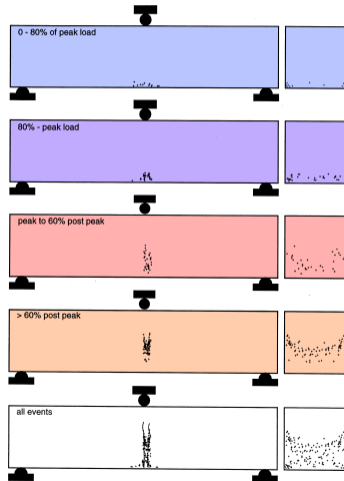
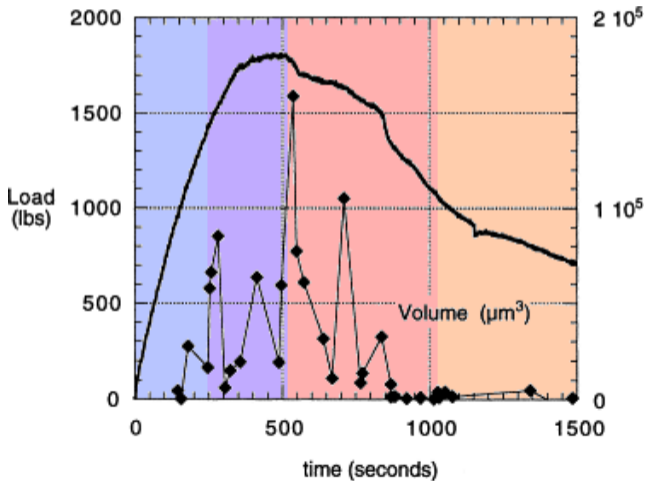
An exemple of structure



A tensile test on concrete (Terrien, 1980)



Quasi-brittle materials: Damaging process (Landis, 1999)



Objectives

Objective of the project

Formulating an anisotropic damage model for quasi-brittle material

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Structure of a damage model

$$\mathcal{V} = \{\boldsymbol{\varepsilon}, \mathbf{D}, \dots\} \quad (\text{Set of variables})$$

$$\rho\psi = \frac{1}{2}\boldsymbol{\varepsilon} : \mathbf{E}(\mathbf{D}) : \boldsymbol{\varepsilon} \quad (\text{State potential})$$

$$\frac{\partial \mathbf{D}}{\partial t} = \dots \quad (\text{Damage evolution})$$

Notations

- ▶ \mathbf{D} damage variable
- ▶ $\mathbf{E}(\mathbf{D})$ effective elasticity tensor

Constraints

- ▶ $\mathbf{E}(\mathbf{D})$ is positive definite
- ▶ Positive dissipation

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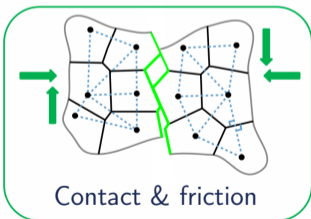
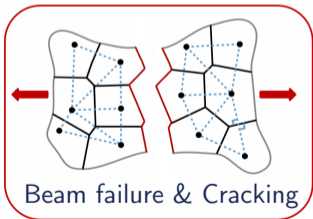
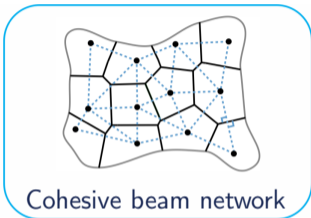
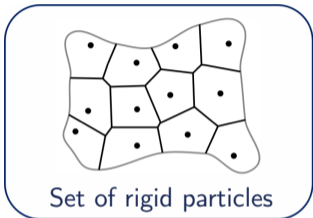
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Objectives of the presentation

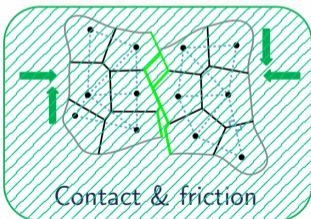
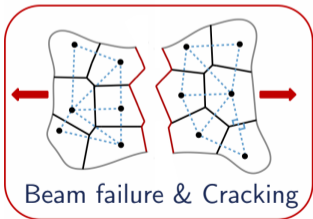
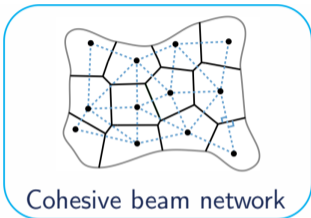
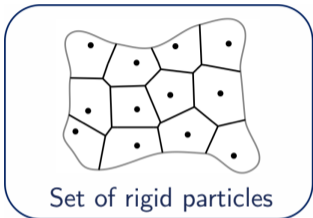
1. Gather data on the behavior of quasi-brittle material
2. Quantify the micro-cracking
3. Model the impact of micro-cracking on the relation between $\boldsymbol{\varepsilon}$ and $\boldsymbol{\sigma}$

Virtual testing

Discrete model – Beam-particle model (Vassaux et al., 2016)

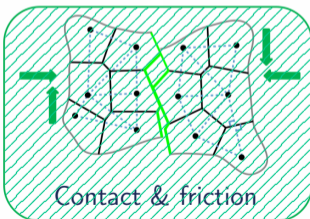
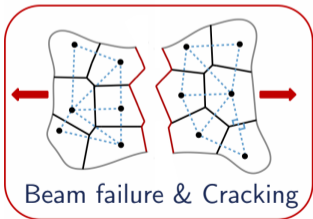
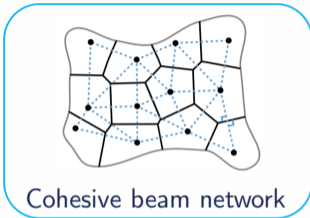
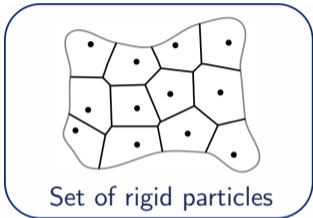


Discrete model – Beam-particle model (Vassaux et al., 2016)



Remark
Contact/friction disabled.

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Info

- ✓ Accurate representation of fracture process (Oliver-Leblond, 2019)
- ✓ Reproducibility
- ✗ Complex to identify

Illustration for a tensile test

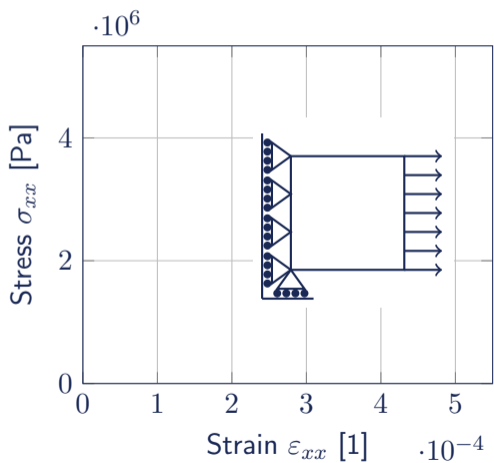


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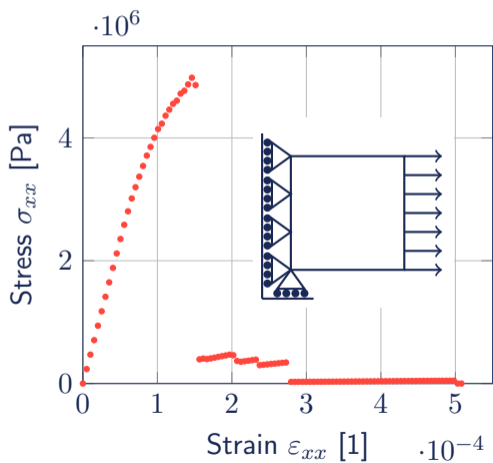
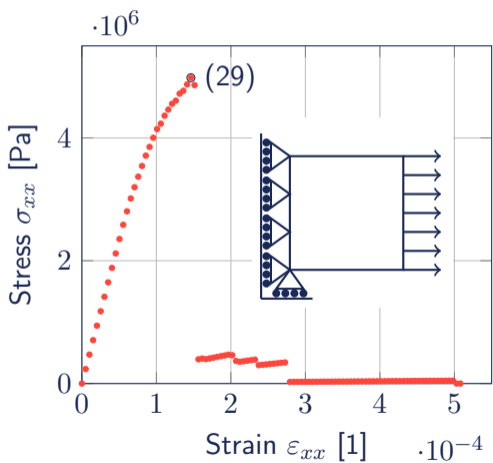


Illustration for a tensile test



Step 29
Stress peak

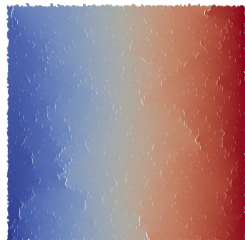
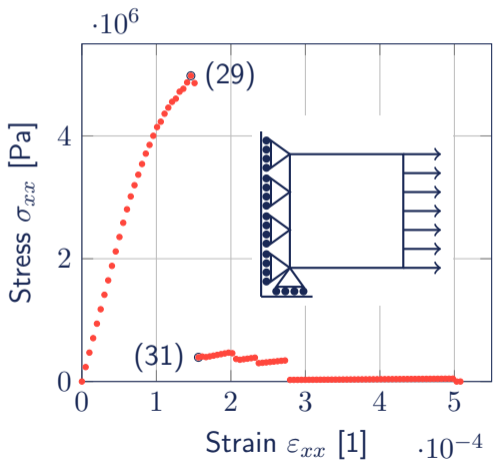
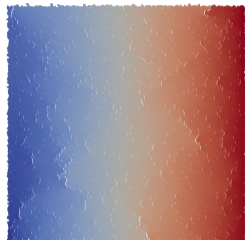


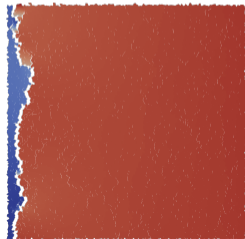
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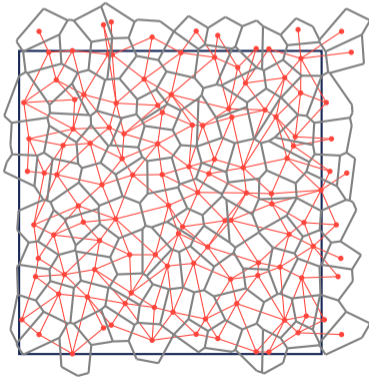
Step 31
Post peak



Measurement of the elasticity tensor – Idea

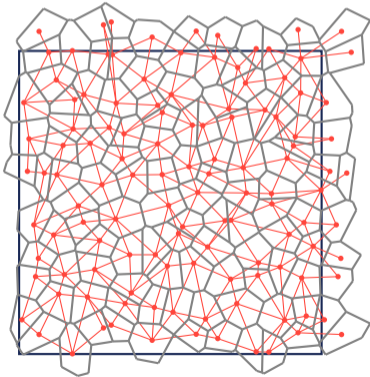
Representative Volume Element
(RVE)

How to measure the effective elasticity
tensor ?



Measurement of the elasticity tensor – Idea

Representative Volume Element (RVE)



How to measure the effective elasticity tensor ?

Given,

- ▶ $\underline{\underline{\varepsilon}}^{(i)}$ – 3 linearly independent strains
- ▶ $\underline{\underline{\sigma}}^{(i)}$ – 3 associated stresses

the effective elasticity tensor is given by,

$$\underline{\underline{E}}(\mathbf{D}) = \left(\left[\underline{\underline{\sigma}}^{(1)} \mid \underline{\underline{\sigma}}^{(2)} \mid \underline{\underline{\sigma}}^{(3)} \right] \left[\underline{\underline{\varepsilon}}^{(1)} \mid \underline{\underline{\varepsilon}}^{(2)} \mid \underline{\underline{\varepsilon}}^{(3)} \right]^{-1} \right)^S$$

$$\text{Kelvin notation: } \underline{\underline{\sigma}}^{(i)} = \left[\sigma_{xx}^{(i)}, \sigma_{yy}^{(i)}, \sqrt{2}\sigma_{xy}^{(i)} \right]^T$$

Measurement of the elasticity tensor – Procedure

1. Apply 3 periodic elastic loadings

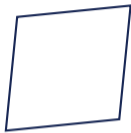
$$\mathbf{u}(\mathbf{x} + \Delta\mathbf{x}) = \mathbf{u}(\mathbf{x}) + \boldsymbol{\varepsilon}_{imp} \cdot \mathbf{x}$$



$$\boldsymbol{\varepsilon}_{imp}^{(i)} \propto \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$



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$$\bar{\boldsymbol{\varepsilon}} = \frac{1}{V} \sum_{b=0}^{N_b} \frac{\mathbf{u}_b^{(1)} + \mathbf{u}_b^{(2)}}{2} \odot \mathbf{n}_b$$

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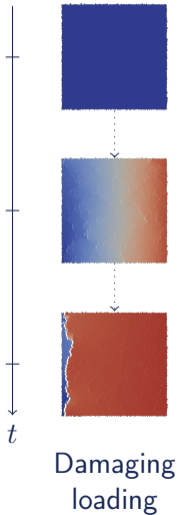
4. Calculate elasticity tensor

$$\underline{\underline{\mathbf{E}}}(\mathbf{D}) = \left(\left[\underline{\underline{\boldsymbol{\sigma}}}^{(1)} \mid \underline{\underline{\boldsymbol{\sigma}}}^{(2)} \mid \underline{\underline{\boldsymbol{\sigma}}}^{(3)} \right] \left[\underline{\underline{\boldsymbol{\varepsilon}}}^{(1)} \mid \underline{\underline{\boldsymbol{\varepsilon}}}^{(2)} \mid \underline{\underline{\boldsymbol{\varepsilon}}}^{(3)} \right]^{-1} \right)^S$$

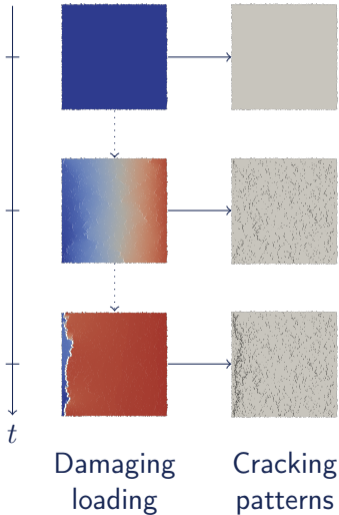
Measurement of the elasticity tensor – Illustration



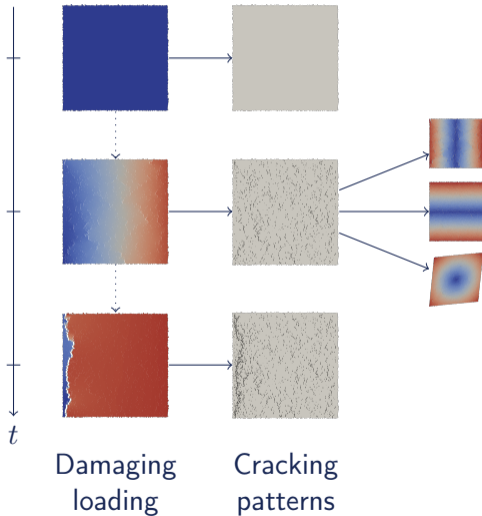
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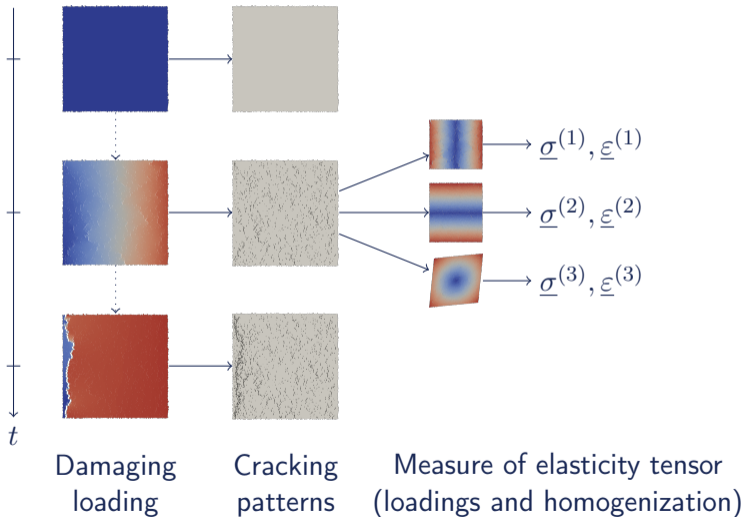
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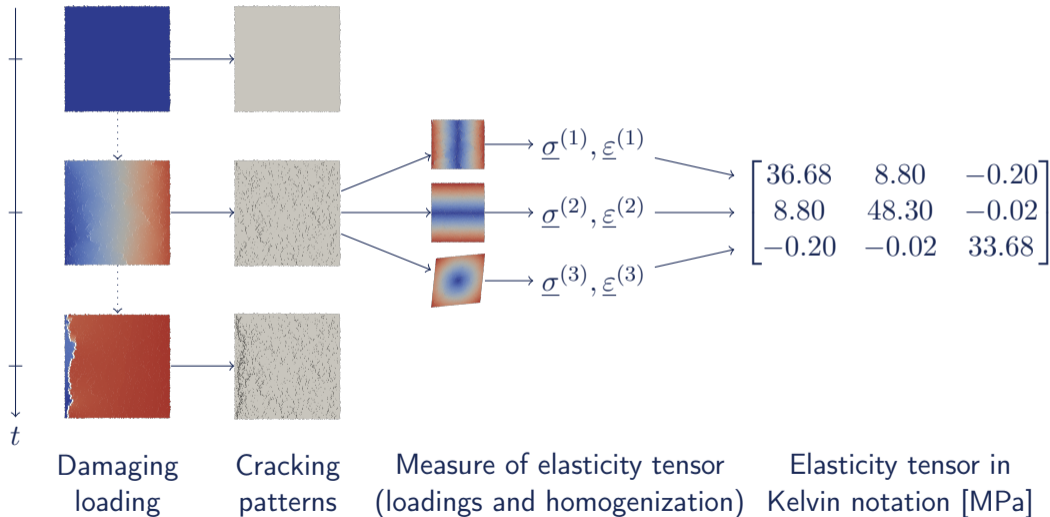
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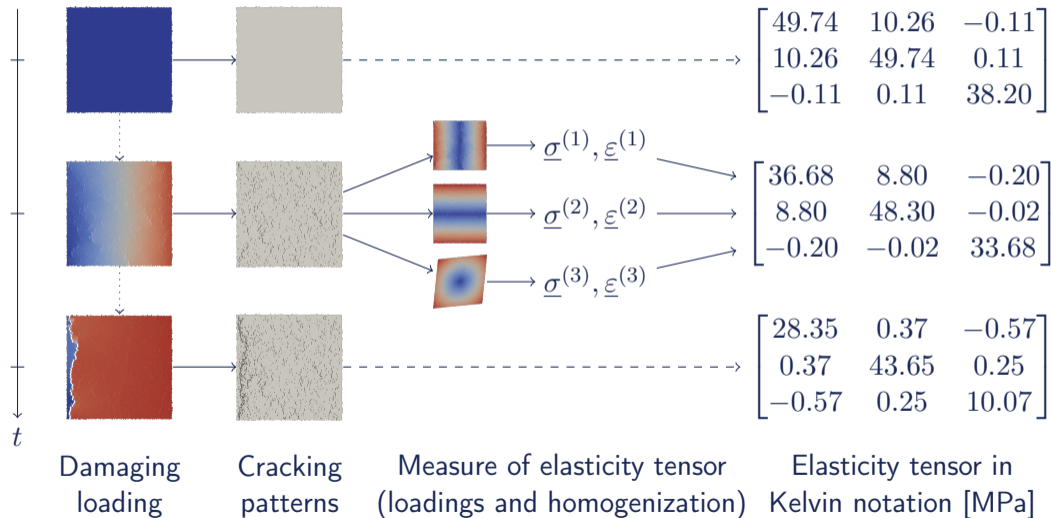
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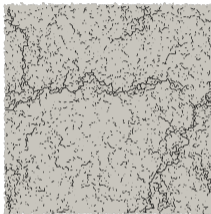
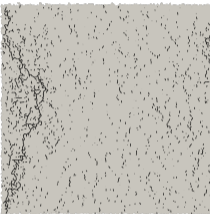
Measurement of the elasticity tensor – Illustration



Virtual testing – Conclusion

Dataset generation

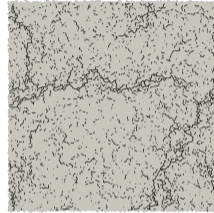
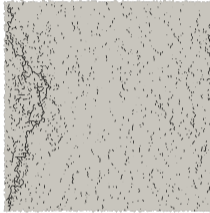
- ▶ 36 micro-structures
- ▶ 21 loadings
- ▶ 756 evolutions
- ▶ 76 356 patterns



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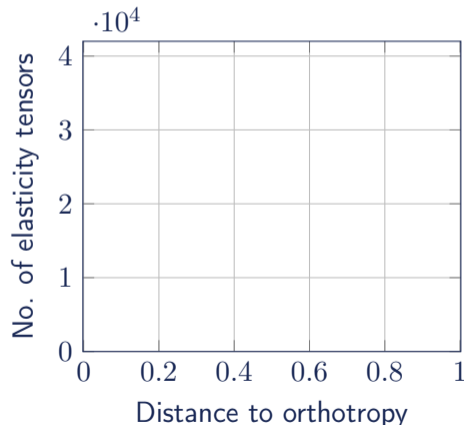
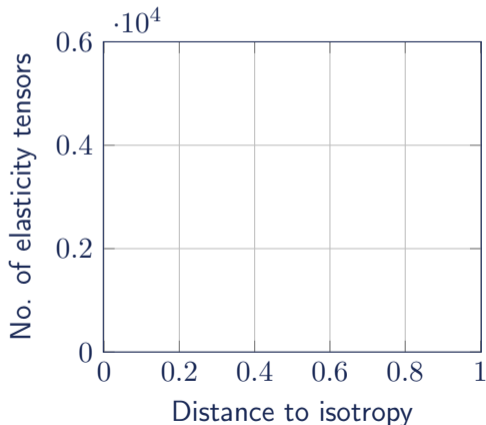
Intermediate conclusion

- ▶ Measurement of elasticity tensor from beam-particle model
- ▶ Generation of a dataset

Damage variable

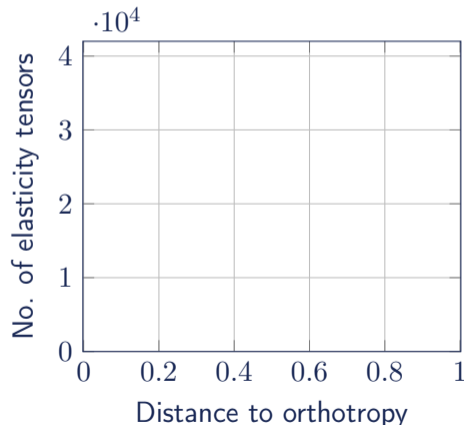
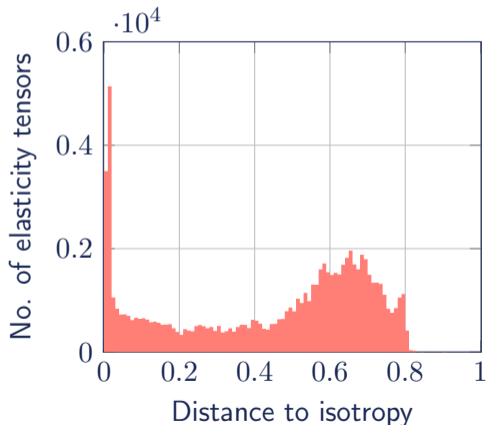
How to represent damage ?

Distance to a symmetry stratum Σ :
$$\Delta_{\Sigma}(\mathbf{E}) = \min_{\mathbf{E}^* \in \Sigma} \frac{\|\mathbf{E} - \mathbf{E}^*\|}{\|\mathbf{E}\|}$$



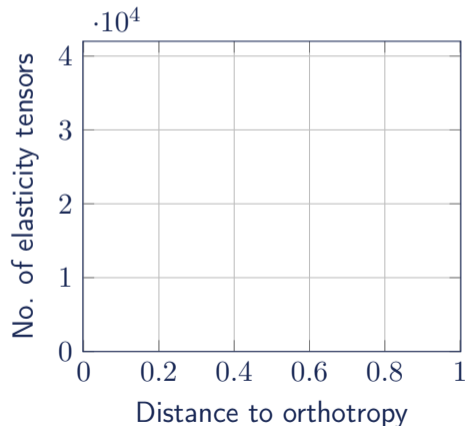
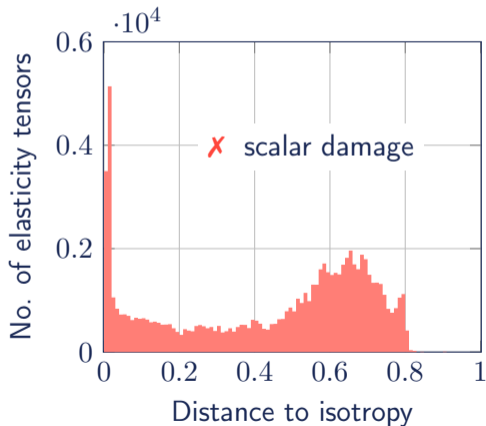
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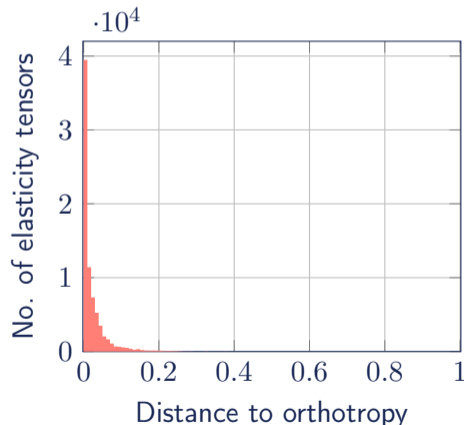
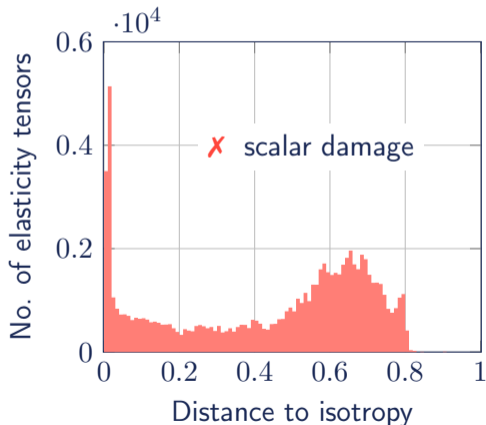
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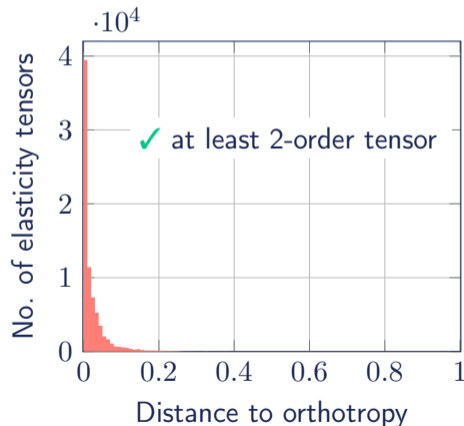
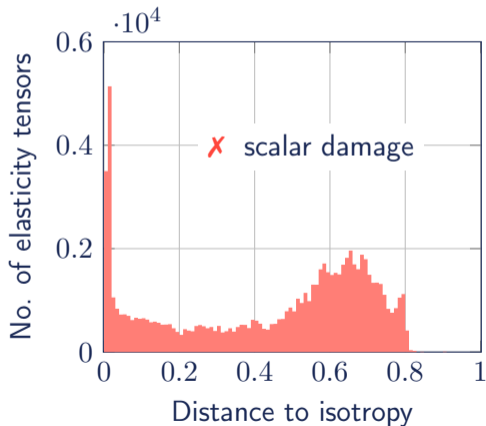
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2D Harmonic decomposition (Backus, 1970), (Blinowski et al., 1996)

$$\mathbf{E} \cong (\mu, \kappa, \mathbf{d}', \mathbf{H}) \in \mathbb{H}^1(\mathbb{R}^2) \oplus \mathbb{H}^1(\mathbb{R}^2) \oplus \mathbb{H}^2(\mathbb{R}^2) \oplus \mathbb{H}^4(\mathbb{R}^2)$$

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$$\text{Reconstruction} \quad (\mu, \kappa, \mathbf{d}', \mathbf{H}) \mapsto \mathbf{E} = \underbrace{2\mu\mathbf{J} + \kappa\mathbf{1}_2 \otimes \mathbf{1}_2}_{\text{Iso}} + \underbrace{\frac{1}{2}(\mathbf{d}' \otimes \mathbf{1}_2 + \mathbf{1}_2 \otimes \mathbf{d}')}_{\text{Dil}} + \mathbf{H}$$

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Decomposition $\mathbf{E} \mapsto (\mu, \kappa, \mathbf{d}', \mathbf{H})$ where $\mathbf{d} = \text{tr}_{12} \mathbf{E}$, $\mathbf{v} = \text{tr}_{13} \mathbf{E}$,

$$\begin{cases} \mu = \frac{1}{8}(2 \text{tr} \mathbf{v} - \text{tr} \mathbf{d}) \\ \kappa = \frac{1}{4} \text{tr} \mathbf{d} \end{cases} \quad \text{are invariants and,} \quad \begin{cases} \mathbf{d}' = \mathbf{d} - \frac{1}{2} \text{tr} \mathbf{d} \mathbf{1}_2 \\ \mathbf{H} = \mathbf{E} - \text{Iso} - \text{Dil} \end{cases} \quad \text{are covariants.}$$

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Damage variable $\mathbf{D} = (\mathbf{d}_0 - \mathbf{d}) \cdot \mathbf{d}_0^{-1} = \mathbf{1}_2 - \frac{1}{2\kappa_0} \mathbf{d} \iff \mathbf{d} = 2\kappa_0(\mathbf{1}_2 - \mathbf{D})$

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Damage variable – Conclusion

Distance to symmetry strata

$$\Delta_{\mathcal{C}}(\mathbf{E}) = \min_{\mathbf{E}^* \in \mathcal{C}} \frac{\|\mathbf{E} - \mathbf{E}^*\|}{\|\mathbf{E}\|}$$

- ▶ Indicates the type of damage variable
- ▶ At least a 2-order damage tensor

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Harmonic decomposition

$$\begin{aligned}(\mu, \kappa, \mathbf{d}', \mathbf{H}) \mapsto \mathbf{E} = & \\ & 2\mu\mathbf{J} + \kappa\mathbf{1}_2 \otimes \mathbf{1}_2 \\ & + \frac{1}{2} (\mathbf{d}' \otimes \mathbf{1}_2 + \mathbf{1}_2 \otimes \mathbf{d}') \\ & + \mathbf{H}\end{aligned}$$

- ▶ Guide the definition of the damage variable $\mathbf{D} = \mathbf{1}_2 - \frac{1}{2\kappa_0}\mathbf{d}$
- ▶ $\kappa(\mathbf{D})$ and $\mathbf{d}'(\mathbf{D})$ are exact
- ▶ $\mu(\mathbf{D})$ and $\mathbf{H}(\mathbf{D})$ need to be modelled

State model

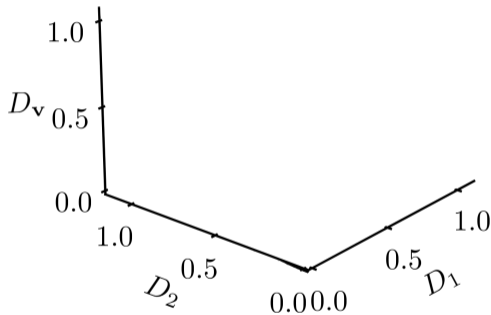
Shear modulus $\mu = \frac{1}{8} (2 \operatorname{tr} \mathbf{v} - \operatorname{tr} \mathbf{d})$ model as a function of damage

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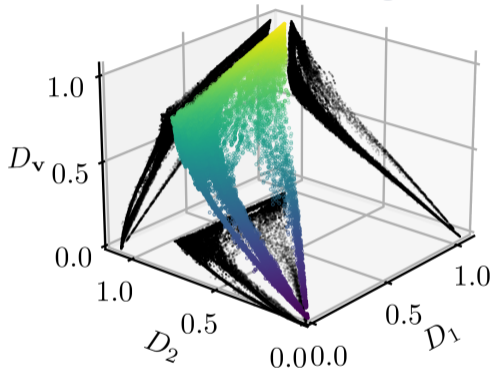


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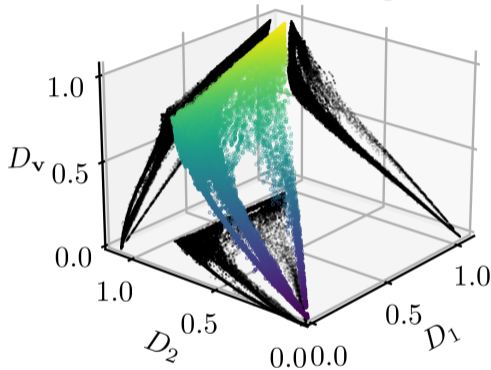
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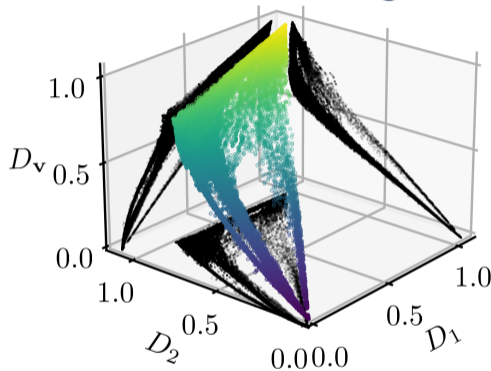
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$$D_{\mathbf{v}}^{\text{m},2} = c_1 I_1(\mathbf{D}) + c_2 I_2(\mathbf{D}) \quad \text{where} \quad \begin{cases} D_{\mathbf{v}}(\mathbf{0}) = 0 & \implies \text{OK} \\ D_{\mathbf{v}}(\mathbf{1}_2) = 1 & \implies c_2 = \frac{1}{2} - c_1 \\ \left. \frac{\partial D_{\mathbf{v}}}{\partial \mathbf{D}} \right|_{\mathbf{D}=\mathbf{0}} = \frac{\kappa_0}{2\mu_0 + \kappa_0} \mathbf{1}_2 & \implies c_1 = \frac{\kappa_0}{2\mu_0 + \kappa_0} \end{cases}$$

Analysis of the harmonic part

Harmonic square reconstruction (Oliver-Leblond et al., 2021)

For an orthotropic elasticity tensor \mathbf{E}_O ,
the harmonic part is

$$\mathbf{H}(\mathbf{E}_O) = \frac{2K_3}{I_2^2} \mathbf{d}' * \mathbf{d}'$$

where:

- ▶ $K_3 = \mathbf{d} : \mathbf{H} : \mathbf{d}$,
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- ▶ for a 2D 2-order harmonic tensor \mathbf{d}' ,
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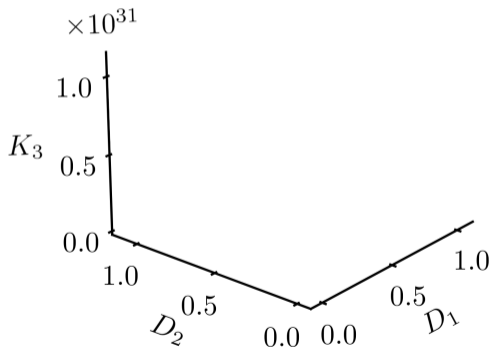
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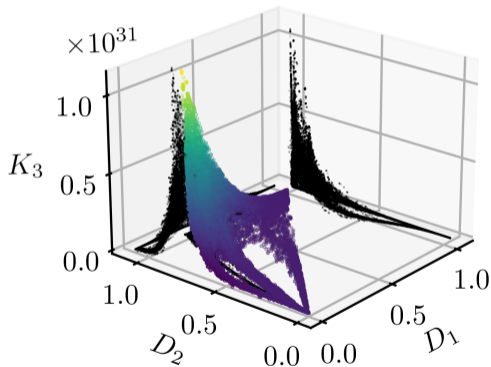
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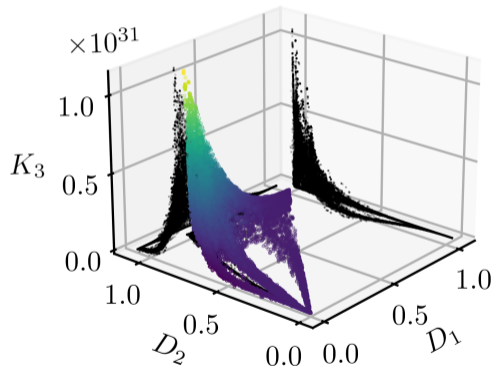
Harmonic part H as a function of damage

Solution 1

Solution 0

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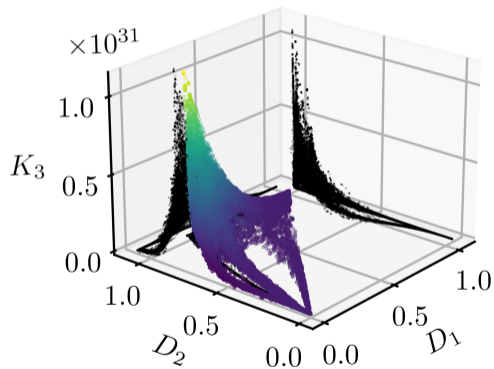


Work in progress: Model $K_3(\mathbf{D})$

Solution 0

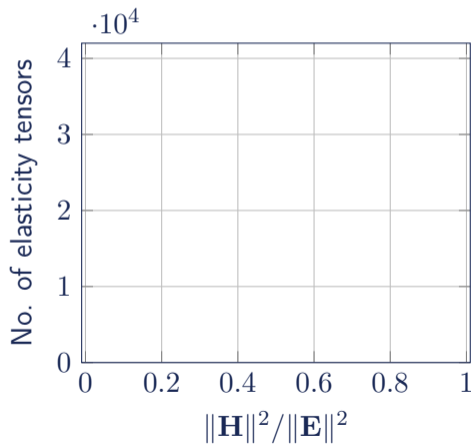
Harmonic part \mathbf{H} as a function of damage

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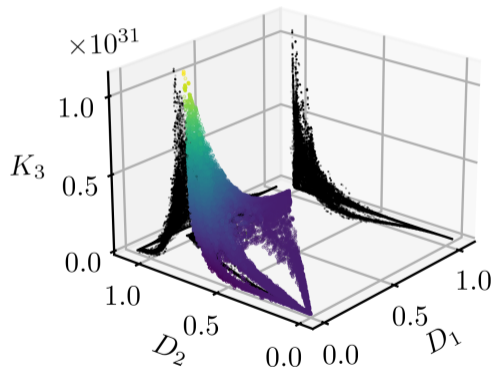
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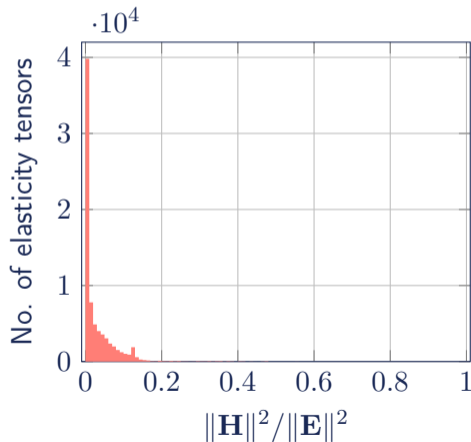
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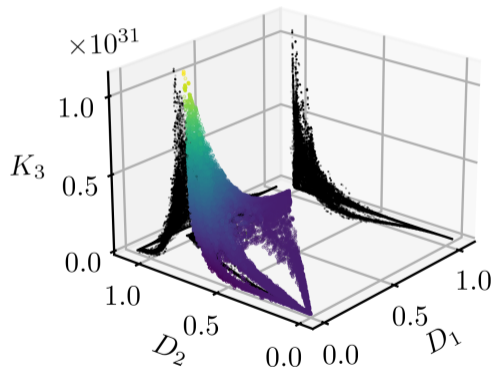
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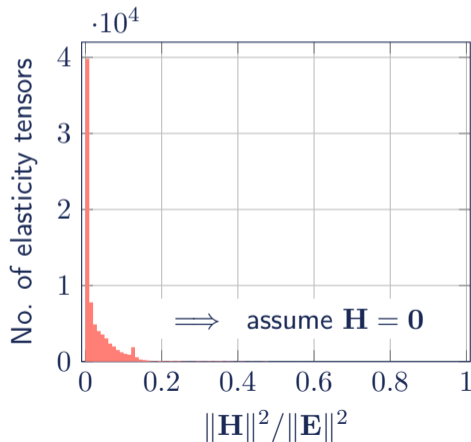
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Summary of model

If \mathbf{E}_0 and \mathbf{D} are known, the elasticity tensor can be modelled as

$$\mathbf{E}(\mathbf{D}) = 2\mu(\mathbf{D})\mathbf{J} + \kappa(\mathbf{D})\mathbf{1}_2 \otimes \mathbf{1}_2 + \frac{1}{2} (\mathbf{d}'(\mathbf{D}) \otimes \mathbf{1}_2 + \mathbf{1}_2 \otimes \mathbf{d}'(\mathbf{D})) + \mathbf{H}(\mathbf{D})$$

where,

$$\mathbf{d}(\mathbf{D}) = 2\kappa_0(\mathbf{1}_2 - \mathbf{D})$$

$$\kappa(\mathbf{D}) = \frac{1}{4} \operatorname{tr} \mathbf{d}$$

$$\mathbf{d}'(\mathbf{D}) = \mathbf{d} - \frac{1}{2} \operatorname{tr} \mathbf{d} \mathbf{1}_2$$

are exact.

$$D_{\mathbf{v}}^{\mathbf{m},2}(\mathbf{D}) = c_1 I_1(\mathbf{D}) + \left(\frac{1}{2} - c_1\right) I_2(\mathbf{D})$$

$$\mu^{\mathbf{m}}(\mathbf{D}) = \frac{1}{8} (2 \operatorname{tr} \mathbf{v}_0 (1 - D_{\mathbf{v}}^{\mathbf{m}}) - \operatorname{tr} \mathbf{d})$$

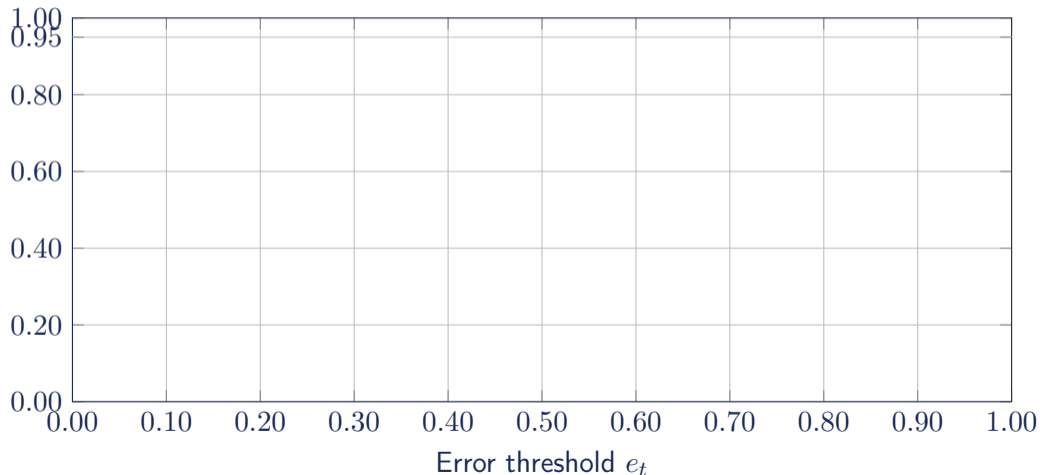
$$\mathbf{H}^{\mathbf{m}}(\mathbf{D}) = \mathbf{0}$$

are approximate.

The parameter $c_1 = \frac{\kappa_0}{2\mu_0 + \kappa_0}$ and the invariants of \mathbf{D} are $I_n = \operatorname{tr}(\mathbf{D}^n)$.

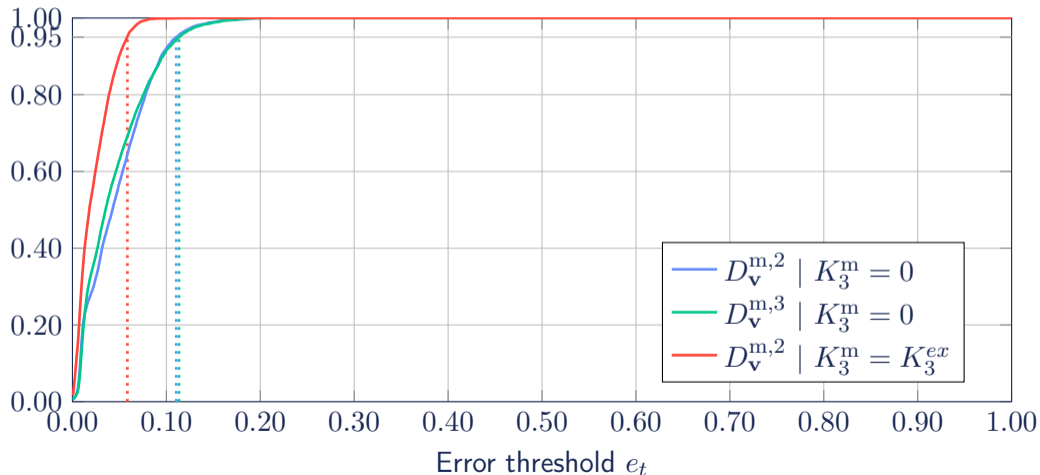
Model error estimation

Proportion of \mathbf{E} s.t. $\frac{\|\mathbf{E} - \mathbf{E}^m\|}{\|\mathbf{E}_0\|} \leq e_t$



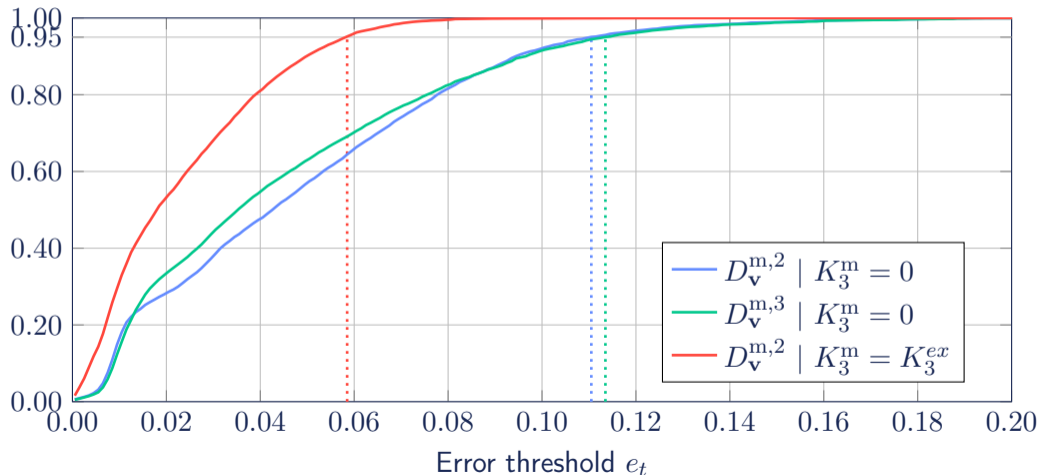
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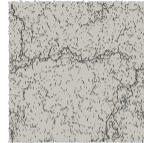
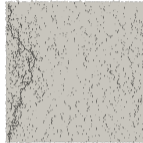


Conclusion

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Objectives of the presentation

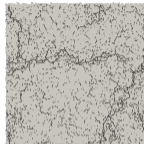
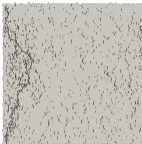
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 - ▶ Virtual testing



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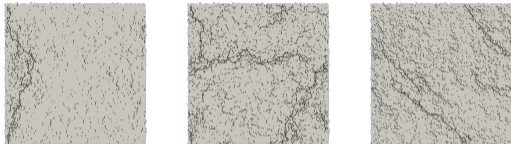
$$\mathbf{D} = \mathbf{1}_2 - \frac{1}{2\kappa_0} \mathbf{d}$$

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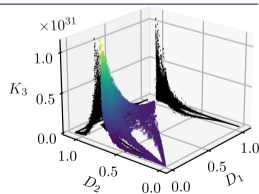
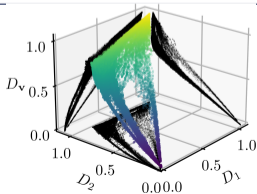
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3. Model the impact of micro-cracking on the relation between ε and σ
 - ▶ Exact models of $\kappa(\mathbf{D})$, $\mathbf{d}'(\mathbf{D})$
 - ▶ Modelling of $\mu(\mathbf{D})$, $\mathbf{H}(\mathbf{D})$



Perspectives

Objective of the project

Formulating an anisotropic damage model for quasi-brittle material

Formulation of a damage model

$$\mathcal{V} = \{\boldsymbol{\varepsilon}, \mathbf{D}, \dots\} \quad (\text{Set of variables})$$

$$\rho\psi = \frac{1}{2}\boldsymbol{\varepsilon} : \mathbf{E}(\mathbf{D}) : \boldsymbol{\varepsilon} \quad (\text{State potential})$$

$$\dot{\mathbf{D}} = \dots \quad (\text{Damage evolution})$$

Constraints

- ▶ $\mathbf{E}(\mathbf{D})$ is positive definite
- ▶ Positive dissipation

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- ▶ Formulate a model of K_3 as a function of \mathbf{D}
- ▶ Formulate an evolution model for \mathbf{D}
- ▶ Study nonlocal damage via beam-particle model

Merci pour votre attention !







Réunion thématique du GDR-GDM, ENS Paris-Saclay, 23/11/2022.

Flavien Loiseau – flavien.loiseau@ens-paris-saclay.fr







Encadré par: Rodrigue Desmorat, Cécile Oliver-Leblond

Université Paris-Saclay, CentraleSupélec, ENS Paris-Saclay, CNRS, LMPS - Laboratoire de Mécanique
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